# Seidel Switching 

Michelle A. Lastrina

# A thesis presented to the faculty of Mount Holyoke College in partial fulfillment of the requirements for the degree of Bachelor of Arts with Honors. 

Department of Mathematics

South Hadley, Massachusetts
May 28, 2006

## Acknowledgements

I would like to thank Profs. Giuliana Davidoff and Harriet Pollatsek for all of their guidance throughout this project, it has been greatly appreciated. Special thanks to Prof. Robert Perlis of Louisiana State University for introducing me to this topic while participating in a Mathematics REU during the summer of 2005. Thanks to Prof. Gregory Quenell of the State Unviersity of New York, Plattsburgh for providing a wonderful starting point with [7]. Thanks to the Mount Holyoke College Mathematics Department for all of their support and the wonderful education they have provided me with. I would also like to thank my friends and family for their support and encouragement.


#### Abstract

Seidel switching is a technique for generating pairs of graphs that are cospectral ${ }^{1}$ but not necessarily isomorphic. We will discuss and prove some important properties related to this graph construction. Cospectral pairs of regular graphs are rarer than cospectral pairs of nonregular graphs. As a result, after looking at how to construct graphs via the Seidel technique, we will look specifically at generating regular pairs of graphs via the Seidel swtiching technique.


[^0]
## Contents

1 Introduction ..... 5
2 Definitions ..... 6
3 Eigenvalues and $k$-walks ..... 9
4 An introduction to Seidel switching ..... 13
5 Seidel switching generates cospectral graphs ..... 14
6 Seidel switching and regularity ..... 23
7 Seidel switching and the Ihara zeta function ..... 30
8 Small, regular Seidel pairs ..... 31
9 Further questions ..... 32
A All 3-walks in $\Gamma_{A}$ and $\Gamma_{B}$ (Combinatorial Proof) ..... 33
B Symmetric matrices have real eigenvalues ..... 47
B. 1 Schur's Lemma ..... 47
B. 2 Spectral Theorem for Hermitian Matrices ..... 50
B. 3 Fundamental Theorem of Real Symmetric Matrices ..... 51

## 1 Introduction

We will be exploring a topic in graph theory known as Seidel switching. It was first introduced in [9] as part of a discussion on equilateral point sets in elliptic space and later explored by Robert Brooks and Gregory Quenell. In [7], Gregory Quenell explored Seidel switching in order to answer the question "can you hear the shape of a graph?" In other words, does the spectrum of a graph determine the structure (or shape) of a graph? In proving that Seidel switching generates cospectral graphs that are not necessarily isomorphic, we can see that the answer to this question is no, graph structure is not determined by its spectrum. This question is directly related to the question posed by Marc Kac in 1966, "can you hear the shape of a drum?" This question explores whether or not a manifold can be determined uniquely by the spectrum. We will be taking the work of Quenell in [7] and expanding on it. Providing proofs of facts and theorems stated, as well as specific examples of facts mentioned throughout.

We will begin by introducing background information to be used throughout. This includes definitions, theorems and proofs that will be important to our results. We denote graphs as $G$ or $\Gamma$. These graphs are undirected, may contain more than one component and we allow for loops and multiple edges. We will
then describe the Seidel switching construction and work through a proof of the fact that graphs constructed via the Seidel technique are cospectral by providing a nontrivial example illustrating the ideas presented. We will also look at the construction with a restriction on it to generate non-isomorphic pairs of regular graphs that are cospectral. We will discuss a conjecture that arises naturally from certain examples and will consider a function, called the Ihara zeta function, that gives us information about the graphs. Throughout we will discuss various properties that arise from Seidel switching and provide specific examples to illustrate these.

## 2 Definitions

Before beginning our discussion of Seidel switching, we introduce some definitions that will be helpful.

Definition 2.1. A graph $G=(V, E)$ is a collection of vertices $v_{i} \in V$ and edges $\epsilon_{i} \in E$ such that each edge has a vertex at each of its endpoints for edges $\epsilon_{i}=\left\{v_{j}, v_{k}\right\}$ where $v_{j}, v_{k} \in V$.

Definition 2.2. The degree, or valency, of vertex $v$ in a graph $G$ is the number of edges incident to $v$, where each loop at $v$ is counted twice.

Definition 2.3. $G$ is regular if each vertex is of the same degree, and $q$ regular if the common degree is $q$.

Definition 2.4. For a graph $G$, a walk from vertex $v$ to vertex $w$ is a sequence of edges

$$
\epsilon_{1} \epsilon_{2} \epsilon_{3} \ldots \epsilon_{n}
$$

such that the initial vertex of $\epsilon_{1}$ is $v$ and the terminal vertex of $\epsilon_{n}$ is $w$ where the terminal vertex of $\epsilon_{j}$ is the initial vertex of $\epsilon_{j+1}$. A closed walk occurs when the initial vertex is the same as the terminal vertex of the walk. We refer to a walk such that $n=k$ as a $k$-walk.

Definition 2.5. A prime walk $C$ is a closed walk without backtracking or a
tail (backtracking that occurs at the last step) and there does not exist a walk $B$ such that $C=B^{k}$ for $k>1[6]$.

Definition 2.6. The adjacency matrix $A$ of $G$ is the symmetric $n \times n$ matrix in which entry $a_{i j}=a_{j i}$ is the number of edges in $G$ with endpoints $\left(v_{i}, v_{j}\right)$. (Note that the diagonal entry $a_{i i}$ is twice the number of loops at vertex i. This is because for an undirected graph, a loop can be traversed in either of two directions.)

Definition 2.7. The set of eigenvalues of $A$ is the graph spectrum of $G$.

Definition 2.8. The length spectrum of $G$ is the sequence

$$
l_{0}(G), l_{1}(G), l_{2}(G) \ldots
$$

where $l_{k}(G)$ is the number of closed $k$-walks in $G$ for integers $k \geq 0$.

Definition 2.9. Isospectral graphs are graphs with the same graph spectrum, or their adjacency matrices have the same eigenvalues.

Definition 2.10. If a pair of graphs are isospectral, they are called cospectral graphs [10].

Definition 2.11. Graphs are length isospectral if they have the same length spectrum.

Definition 2.12. A complete graph $K_{n}$ is a graph where each pair of vertices is connected by an edge. $K_{n}$ will have $n$ vertices, $\frac{n(n+1)}{2}$ edges and is regular of degree $n-1$.

Definition 2.13. Two graphs $G_{1}$ and $G_{2}$ are said to be isomorphic if there is a 1-1 and onto mapping $f: V_{1} \rightarrow V_{2}$ such that $\left\{v_{i}, v_{j}\right\} \in E_{1}$ if and only if $\left\{f\left(v_{i}\right), f\left(v_{j}\right)\right\} \in E_{2}$.

Definition 2.14. The automorphism group, $\boldsymbol{A} \boldsymbol{u t}(\boldsymbol{G})$, of a graph $G$ is the group of isomorphisms from $G$ to $G$.

Definition 2.15. The symmetric group $S_{n}$ of degree $n$ is the group of all permutations on $n$ elements. $S_{n}$ is therefore a permutation group of order $n$ !.

We note that every group of order $n$ is isomorphic to a subgroup of $S_{n}$.

Definition 2.16. The dihedral group $D_{4}$ is the group generated by the permutations (1234) and (13) and corresponds to the symmetries of the square.

Definition 2.17. A graph $\Gamma$ is $\boldsymbol{m d 2}$, or minimal degree 2, provided the degree of each vertex is at least 2.

Hence such a $\Gamma$ is not a tree and does not contain any vertices of degree zero.

Definition 2.18. The Ihara zeta function of a regular graph $\Gamma$ is given by
the following infinite product

$$
\mathbf{Z}_{\Gamma}(u)=\prod_{\text {primes } C \in \Gamma}\left(1-u^{\operatorname{deg} C}\right)^{-1}
$$

for prime walks $C$ of $\Gamma$. Where deg $C$ is the number of edges in $C$.

We also have the following:

Theorem 2.19. Ihara's Theorem: If $\Gamma$ is a connected $(q+1)$-regular graph with adjacency matrix $A$, $n$ vertices and e edges, then the Ihara zeta function is defined as the following rational function

$$
Z_{\Gamma}(u)=\frac{\left(1-u^{2}\right)^{n-e}}{\operatorname{det}\left(I-A u+Q u^{2}\right)} .
$$

Here $Q=q I$ is the diagonal matrix where $d$ is the degree of the vertices. ${ }^{2}$

For a proof of Ihara's Theorem see [8] pp.417-418.

[^1]
## 3 Eigenvalues and $k$-walks

The theorems and corresponding proofs of this section are an important part of [7] to show that two graphs have the same length spectrum if and only if they have the same spectrum. This will then be used in the proof that Seidel switching produces cospectral graphs. One conclusion that will we be using in this section is the fact that because $A$ is symmetric, its eigenvalues will be real. For a proof of this, we refer you to section B of the appendix.

Theorem 3.1. Let $A=\left(a_{i j}\right)$ be the adjacency matrix of an undirected graph $G$. For each integer $k \geq 0$, the number of $k$-walks from $v_{i}$ to $v_{j}$ in $G$ is equal to

$$
\left[A^{k}\right]_{i j}
$$

the $i j^{\text {th }}$ entry of the $k^{\text {th }}$ power of $A$.

Proof. We will prove this theorem using induction.
Let $G$ be an undirected graph with vertices $v_{1}, v_{2}, \ldots, v_{n}$. Let $A$ be the adjacency matrix of $G$.

We will show that for all integers $k \geq 0$,

$$
\left[A^{k}\right]_{i j}=\text { the number of } k \text {-walks from } v_{i} \text { to } v_{j}
$$

$n=1:$

$$
A^{1}=A \Rightarrow\left[A^{1}\right]_{i j}=[A]_{i j}
$$

The entry $a_{i j}$ equals the number of edges between $v_{i}$ and $v_{j}$ (by the definition of adjacency matrix), but this is the same as the number of 1 -walks from $v_{i}$ to $v_{j}$ for $i \neq j$.

We recall from earlier that for a loop at $v_{i}$, we count two 1 -walks from $v_{i}$ to $v_{i}$ since a loop contributes to the valency twice.
$n=k-1$ : Assume $\left[A^{k-1}\right]_{i j}=$ the number of $k-1$-walks from $v_{i}$ to $v_{j}$. (This is our induction hypothesis.)
$n=k$ : Assuming the induction hypothesis, we want to show that

$$
\left[A^{k}\right]_{i j}=\text { the number of } k \text {-walks from } v_{i} \text { to } v_{j}
$$

Let $A=\left(a_{i j}\right)$ and $A^{k-1}=\left(b_{i j}\right)$. So

$$
A^{k}=A A^{k-1}=A^{k-1} A
$$

and the $i j$ entry of $A^{k}$ can be found by multiplying the $i^{\text {th }}$ row of $A$ by the $j^{\text {th }}$ column of $A^{k-1}$. Hence,

$$
\left[A^{k}\right]_{i j}=a_{i 1} b_{1 j}+a_{i 2} b_{2 j}+\ldots+a_{i n} b_{n j}
$$

for all $i, j \in\{1,2, \ldots, n\}$.

We will now look at each term of the above sum:

$$
\begin{gathered}
a_{i 1}=\text { the number of edges between } v_{i} \text { and } v_{1} \\
b_{1 j}=\text { the number of } k-1 \text {-walks between } v_{1} \text { and } v_{j} \\
\text { (by the induction hypothesis). }
\end{gathered}
$$

Clearly, any edge between $v_{i}$ and $v_{1}$ can connect with any $k-1$-walk from $v_{1}$ to $v_{j}$ and form a $k$-walk from $v_{i}$ to $v_{j}$ with $v_{1}$ as its second vertex.

By multiplication, we now have

$$
\begin{aligned}
& a_{i 1} b_{1 j}=\text { the number of } k \text {-walks from } v_{i} \text { to } v_{j} \text { in } G \\
& \text { with } v_{1} \text { as the second vertex of the walk. }
\end{aligned}
$$

We may now generalize this for all $m \in\{1,2, \ldots, n\}$ to obtain the following:

$$
\begin{aligned}
& a_{i m} b_{m j}=\text { the number of } k \text {-walks from } v_{i} \text { to } v_{j} \text { in } G \\
& \text { such that } v_{m} \text { is the second vertex of the walk. }
\end{aligned}
$$

For every $k$-walk from $v_{i}$ to $v_{j}$ there is a vertex of $G$ that is the second vertex of the walk. Thus, the total number of $k$-walks from $v_{i}$ to $v_{j}$ is

$$
a_{i 1} b_{1 j}+a_{i 2} b_{2 j}+\ldots+a_{i n} b_{n j}
$$

From earlier, we know that this is $\left[A^{k}\right]_{i j}$. Thus,

$$
\left[A^{k}\right]_{i j}=\text { the number of } k \text {-walks from } v_{i} \text { to } v_{j} \text { in } G
$$

We can now use this conclusion to prove the following theorem that will indicate the direct relationship between the spectrum and length spectrum of a graph $G$.

Theorem 3.2. Let $G$ be a graph with adjacency matrix $A$ and let $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{N}$ be the eigenvalues of $A$. For each integer $k \geq 0$, the total number of closed $k$-walks in $G$ is equal to

$$
\lambda_{1}^{k}+\lambda_{2}^{k}+\ldots+\lambda_{N}^{k}
$$

Proof. The total number of closed $k$-walks in $G$ equals the sum of the number of closed $k$-walks at each vertex $v_{i}$ in $G$. A closed $k$-walk at a vertex $v_{i}=\left[A^{k}\right]_{i i}$.

Let us recognize the following lemma and corresponding proof.

Lemma 3.3. For a diagonalizable matrix $A$ and its corresponding diagonal matrix $D=Q A Q^{-1}, \operatorname{tr}(A)=\operatorname{tr}(D)$.

Proof. We first show $\operatorname{tr}(A B)=\operatorname{tr}(B A)$.

$$
\sum_{i}[A B]_{i i}=\sum_{i} \sum_{k} a_{i k} b_{k i}
$$

$$
\begin{aligned}
= & \sum_{k} \sum_{i} b_{k i} a_{i k} \\
& =\sum_{k}[B A]_{k k}
\end{aligned}
$$

We now apply $\operatorname{tr}(A B)=\operatorname{tr}(B A)$ to get

$$
\begin{gathered}
\operatorname{tr}\left(Q A Q^{-1}\right)=\operatorname{tr}\left(Q A Q^{-1}\right) \\
=\operatorname{tr}\left(A Q^{-1} Q\right) \\
=\operatorname{tr}(A)
\end{gathered}
$$

This tells us, since the entries along the diagonal of a diagonal matrix are its eigenvalues, $\operatorname{tr}(D)=$ the sum of the eigenvalues $=\operatorname{tr}(A)$.

We now have the total number of closed $k$-walks in $G=$

$$
\sum_{i=1}^{N}\left[A^{k}\right]_{i i}=\operatorname{tr}\left(A^{k}\right) .
$$

Since $\lambda_{i}$ are eigenvalues of $A, \lambda_{i}^{k}$ are eigenvalues of $A^{k}$.

Thus, we have

$$
\operatorname{tr}\left(A^{k}\right)=\lambda_{1}^{k}+\lambda_{2}^{k}+\ldots+\lambda_{N}^{k} .
$$

## 4 An introduction to Seidel switching

Let us begin by explaining how to construct a pair of cospectral graphs using the Seidel switching technique. This can also be found in [7] pp. 5-6.

Given the graphs $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right)$ such that $G_{2}$ is regular and has an even number of vertices, we create a set of edges $\mathcal{E}$. The set $\mathcal{E}$ joins each vertex in $V_{1}$ to half of the vertices in $V_{2}$. There is no predetermined way to choose $\mathcal{E}$. We also form the set of edges $\mathcal{E}^{\mathcal{C}}$ such that there is an edge in $\mathcal{E}^{\mathcal{C}}$ between a vertex in $V_{1}$ and a vertex in $V_{2}$ if and only if there is no edge between these vertices in $\mathcal{E}$.

These two edge sets form two different graphs $\Gamma_{A}$ and $\Gamma_{B}$ such that

$$
\Gamma_{A}=\left(V_{A}, E_{A}\right)=\left(V_{1} \cup V_{2}, E_{1} \cup E_{2} \cup \mathcal{E}\right)
$$

and

$$
\Gamma_{B}=\left(V_{B}, E_{B}\right)=\left(V_{1} \cup V_{2}, E_{1} \cup E_{2} \cup \mathcal{E}^{\mathcal{C}}\right)
$$

We provide illustrations to show this construction more clearly. We begin with $G_{1}$ and $G_{2}$ as shown in Figure 4.1 on p.16a. Note that $G_{2}$ has an even number of vertices and is 2-regular. We then introduce the sets $\mathcal{E}$ and $\mathcal{E}^{\mathcal{C}}$ in Figure 4.2 on p.16a. We can now construct the graphs $\Gamma_{A}$ and $\Gamma_{B}$ as shown in Figure 4.3 on p.16a. We see that in this example, $\Gamma_{A}$ and $\Gamma_{B}$ are non-isomorphic. To see


Figure 4.1


Figure $4.2: G_{1}$ and $G_{2}$ with $\varepsilon$ and $\varepsilon^{c}$

this, we can compare the location of the loops in $\Gamma_{A}$ and $\Gamma_{B}$.

Definition 4.1. We can refer to the construction involving $G_{1}, G_{2}, \mathcal{E}, \mathcal{E}^{\mathcal{C}}$, $\Gamma_{A}$, and $\Gamma_{B}$ as the Seidel pair $\left(G_{1}, G_{2}, \mathcal{E}\right)$.

Definition 4.2. $\left(\Gamma_{A}, \Gamma_{B}\right)$ is a Seidel switch of $\left(G_{1}, G_{2}\right)$.

The dependence on $\mathcal{E}$ is important because a different choice of the edge set $\mathcal{E}$ combined with $G_{1}$ and $G_{2}$ can create a different pair of $\Gamma_{A}$ and $\Gamma_{B}$ as the following example shows. While [7] alludes to this fact by noting that $\mathcal{E}$ uniquely identifies a Seidel pair, it does not directly state the following:

Example 4.3. Given graphs $G_{1}$ and $G_{2}$, there may exist more than one choice for $\mathcal{E}$.

Figures 4.4-4.8 on pp.16b-c illustrate this example. We can see that we begin with the same $G_{1}$ and $G_{2}$ such that they both have four vertices and $G_{1}$ and $G_{2}$ are both 2-regular. However, we choose two different edge sets $\mathcal{E}$, as shown, that generate two different Seidel switches of $\left(G_{1}, G_{2}\right)$. In this case we produce two pairs of isomorphic graphs.


166


Figure 4.4


Figure $4.5: G_{1}$ and $G_{2}$ with First choice of $\varepsilon$


Figure $4.6: \Gamma_{A}$ for first choice of $\varepsilon$


Figure 4.7: $G_{1}$ and $G_{2}$ with second choice of $\varepsilon$


Figure 4.8: $\Gamma_{\mathrm{A}}$ for second choice of $\varepsilon$

## 5 Seidel switching generates cospectral graphs

Theorem 5.1. Graphs constructed via the Seidel technique are cospectral.

Section 4 of [7] provides a combinatorial proof that shows graphs constructed via the Seidel technique are length isospectral and thus cospectral. We now outline this proof and illustrate it with the following nontrivial example.

We begin with the Seidel pair $\left(G_{1}, G_{2}, \mathcal{E}\right)$ as shown in Figures 5.1-5.3 on pp.18ab. We then provide $(v, w, k) A$ and $B$-patches as defined by [7].

For vertices $v$ and $w$ in $V_{1}$ and a nonnegative integer $k$ (for our example we will let $v=$ vertex $1, w=$ vertex 2 , and $k=3$ ), we define a $(v, w, k) A$-patch to be the sequence of edges

$$
\epsilon_{0} \epsilon_{1} \epsilon_{2} \ldots \epsilon_{k} \epsilon_{k+1}
$$

in which

1. $\epsilon_{0} \in \mathcal{E}$ and $\epsilon_{k+1} \in \mathcal{E}$
2. $\epsilon_{0}$ begins at vertex $v$ and $\epsilon_{k+1}$ ends at $w$
3. $\epsilon_{i} \in E_{2}$ for $i=0, \ldots k$
4. If $\epsilon_{i}$ ends at vertex $u$, then $\epsilon_{i+1}$ begins at vertex $u$ for $i=0, \ldots, k$.


Figure 5.1


Figure 5.2

$18 b$

Figure 5,3

Thus, a $(v, w, k) A$-patch is a walk in $\Gamma_{A}$ from $v$ to $w$ where only the first and last edges are in $\mathcal{E}$. We also have a $(v, w, k) B$-patch that is a walk from $v$ to $w$ in $\Gamma_{B}$ where only the first and last edges are in $\mathcal{E}^{\mathcal{C}}$. We define this formally as a sequence of directed edges

$$
\epsilon_{0} \epsilon_{1} \epsilon_{2} \ldots \epsilon_{k} \epsilon_{k+1}
$$

such that

1. $\epsilon_{0} \in \mathcal{E}^{\mathcal{C}}$ and $\epsilon_{k+1} \in \mathcal{E}^{\mathcal{C}}$
2. $\epsilon_{0}$ begins at vertex $v$ and $\epsilon_{k+1}$ ends at $w$
3. $\epsilon_{i} \in E_{2}$ for $i=0, \ldots k$
4. If $\epsilon_{i}$ ends at vertex $u$, then $\epsilon_{i+1}$ begins at vertex $u$ for $i=0, \ldots, k$.

We provide examples of both an $A$-patch and $B$-patch that can be seen in Figures 5.2 and 5.3 on pp.18a-b. For our example, we can see that the walk

$$
1 \rightarrow 8 \rightarrow 6 \rightarrow 7 \rightarrow 8 \rightarrow 4
$$

in $\Gamma_{A}$ is an example of a $(1,4,3) A$-patch. The walk

$$
1 \rightarrow 11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow 4
$$

in $\Gamma_{B}$ is an example of a $(1,4,3) B$-patch. Here $(c w)$ denotes clockwise movement around the loop at vertex 11 .

We are then presented with the following lemma that is a significant part of the proof of the validity of Seidel switching:

Lemma 5.2. Given a Seidel pair $\left(G_{1}, G_{2}, \mathcal{E}\right)$, for each pair $v$ and $w$ of vertices in $V_{1}$ and each non-negative integer $k$, the number of $(v, w, k) A$-patches is equal to the number of $(v, w, k) B$-patches.

To show this we are first required to show the following result.

Lemma 5.3. Let $G$ be an r-regular graph. Given a vertex $v$ in $G$ and a nonnegative integer $k$, the number of $k$-walks in $G$ which begin at $v$ is $r^{k}$. Also, the number of $k$-walks in $G$ which end at $v$ is $r^{k}$.

We can see this is true by examining our example, let $k=3$. We thus move on to prove Lemma 5.2. We begin by considering vertices $v$ and $w$ in $G_{1}$ and partitioning the vertices of $V_{2}$ as follows:

$$
V_{2}=V_{(v, A)} \cup V_{(v, B)}
$$

where $V_{(v, A)}$ is the set of vertices in $V_{2}$ adjacent to $v$ in $\Gamma_{A}$ and $V_{(v, B)}$ is the set of vertices in $V_{2}$ that are adjacent to $v$ in $\Gamma_{B}$. We then create another partition in the same sense:

$$
V_{2}=V_{(w, A)} \cup V_{(w, B)}
$$

where the vertices in $V_{(w, A)}$ are adjacent to $w$ in $\Gamma_{A}$ and the vertices in $V_{(w, B)}$ are adjacent to $w$ in $\Gamma_{B}$. For our example, the partitions are as follows:

- $V_{(v, A)}=$ vertices 6,7 , and 8
- $V_{(v, B)}=$ vertices 9,10 and 11
- $V_{(w, A)}=$ vertices 8,9 , and 10
- $V_{(w, B)}=$ vertices 6,7 , and 11

We can also note that the following holds for our example, and is equal to 3 :

$$
\left|V_{(v, A)}\right|=\left|V_{(v, B)}\right|=\left|V_{(w, A)}\right|=\left|V_{(w, B)}\right|=\frac{\left|V_{2}\right|}{2} .
$$

We then partition all of the $k$-walks in $G_{2}$ into four sets,

$$
W_{A A} \cup W_{A B} \cup W_{B A} \cup W_{B B}
$$

according to where their beginning and ending vertices lie. This is done as follows:

- $W_{A A}$ contains $k$-walks beginning in $V_{(v, A)}$ and ending in $V_{(w, A)}$.
- $W_{A B}$ contains $k$-walks beginning in $V_{(v, B)}$ and ending in $V_{(w, A)}$.
- $W_{B A}$ contains $k$-walks beginning in $V_{(v, A)}$ and ending in $V_{(w, B)}$.
- $W_{B B}$ contains $k$-walks beginning in $V_{(v, B)}$ and ending in $V_{(w, B)}$. For our example, we can now partition all 3-walks in $G_{2}$.
$W_{A A}$ : We recall that these are the 3-walks beginning in $V_{(v, A)}$ and ending in $V_{(w, A)}$. Here we will have 3-walks beginning at vertices 6,7 , and 8 and ending at vertex 8 , as listed below:
- $6 \rightarrow 8 \rightarrow 6 \rightarrow 8$
- $6 \rightarrow 8 \rightarrow 7 \rightarrow 8$
- $6 \rightarrow 7 \rightarrow 6 \rightarrow 8$
- $7 \rightarrow 8 \rightarrow 6 \rightarrow 8$
- $7 \rightarrow 8 \rightarrow 7 \rightarrow 8$
- $7 \rightarrow 6 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 6 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 7 \rightarrow 6 \rightarrow 8$

Here we can see that $\left|W_{A A}\right|=8$.
$W_{A B}$ : All 3-walks in $G_{2}$ beginning in $V_{(v, B)}$ and ending in $V_{(w, A)}$. The beginning vertices will be 9 and 10 , and the ending vertices will be 9 and 10 . Note that here we denote $9 \rightarrow(a) 10$ and $9 \rightarrow(b) 10$ to indicate the difference between the two edges connecting vertices 9 and 10 .

- $9 \rightarrow(a) 10 \rightarrow(b) 9 \rightarrow(b) 10$
- $9 \rightarrow(a) 10 \rightarrow(b) 9 \rightarrow(a) 10$
- $9 \rightarrow(a) 10 \rightarrow(a) 9 \rightarrow(b) 10$
- $9 \rightarrow(a) 10 \rightarrow(a) 9 \rightarrow(a) 10$
- $9 \rightarrow(b) 10 \rightarrow(b) 9 \rightarrow(b) 10$
- $9 \rightarrow(b) 10 \rightarrow(b) 9 \rightarrow(a) 10$
- $9 \rightarrow(b) 10 \rightarrow(a) 9 \rightarrow(b) 10$
- $9 \rightarrow(b) 10 \rightarrow(a) 9 \rightarrow(a) 10$
- $10 \rightarrow(a) 9 \rightarrow(b) 10 \rightarrow(b) 9$
- $10 \rightarrow(a) 9 \rightarrow(b) 10 \rightarrow(a) 9$
- $10 \rightarrow(a) 9 \rightarrow(a) 10 \rightarrow(b) 9$
- $10 \rightarrow(a) 9 \rightarrow(a) 10 \rightarrow(a) 9$
- $10 \rightarrow(b) 9 \rightarrow(b) 10 \rightarrow(b) 9$
- $10 \rightarrow(b) 9 \rightarrow(b) 10 \rightarrow(a) 9$
- $10 \rightarrow(b) 9 \rightarrow(a) 10 \rightarrow(b) 9$
- $10 \rightarrow(b) 9 \rightarrow(a) 10 \rightarrow(a) 9$
$\left|W_{A B}\right|=16$
$W_{B A}$ : We have all 3-walks in $G_{2}$ beginning in $V_{(v, A)}$ and ending in $V_{(w, B)}$. The beginning vertices will be 6, 7 and 8 , and the ending vertices will be 6 and 7 .
- $6 \rightarrow 8 \rightarrow 6 \rightarrow 7$
- $6 \rightarrow 8 \rightarrow 7 \rightarrow 6$
- $6 \rightarrow 7 \rightarrow 8 \rightarrow 6$
- $6 \rightarrow 7 \rightarrow 8 \rightarrow 7$
- $6 \rightarrow 7 \rightarrow 6 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 6 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 7 \rightarrow 6$
- $7 \rightarrow 6 \rightarrow 7 \rightarrow 6$
- $7 \rightarrow 6 \rightarrow 8 \rightarrow 6$
- $7 \rightarrow 6 \rightarrow 8 \rightarrow 7$
- $8 \rightarrow 6 \rightarrow 7 \rightarrow 6$
- $8 \rightarrow 6 \rightarrow 8 \rightarrow 6$
- $8 \rightarrow 6 \rightarrow 8 \rightarrow 7$
- $8 \rightarrow 7 \rightarrow 6 \rightarrow 7$
- $8 \rightarrow 7 \rightarrow 8 \rightarrow 6$
- $8 \rightarrow 7 \rightarrow 8 \rightarrow 7$
$\left|W_{B A}\right|=16$
$W_{B B}$ : All 3-walks from $V_{(v, B)}$ to $V_{(w, B)}$ beginning and ending at vertex 11 . Here we use $11 \rightarrow(c w) 11$ and $11 \rightarrow(c c w) 11$ to denote the difference between clockwise and counterclockwise movement around the loop at vertex 11.
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
$\left|W_{B B}\right|=8$

We can see that $W_{A A} \cup W_{A B}$ contains all $k$-walks in $G_{2}$ that begin at a vertex in $V_{(v, A)}$ and end in $V_{2}$. Since $G_{2}$ is $r$-regular, in the case of our example 2-regular, and there are exactly $\frac{\left|V_{2}\right|}{2}$, or 3 , vertices in $V_{(v, A)}$, we apply Lemma 5.3 to get

$$
\begin{equation*}
\left|W_{A A}\right|+\left|W_{A B}\right|=\left|V_{(v, A)}\right| r^{k}=\frac{\left|V_{2}\right|}{2} r^{k} \tag{5.1}
\end{equation*}
$$

For our example,

$$
\begin{equation*}
8+16=3 * 2^{3}=\frac{6}{2} * 2^{3}=32 \tag{5.2}
\end{equation*}
$$

We also have that $W_{A B} \cup W_{B B}$ contains all of the $k$-walks, or 3-walks, in $G_{2}$ beginning in $V_{2}$ and ending at a vertex in $V_{(w, B)}$. This gives us

$$
\begin{equation*}
\left|W_{A B}\right|+\left|W_{B B}\right|=\left|V_{(w, B)}\right| r^{k}=\frac{\left|V_{2}\right|}{2} r^{k} \tag{5.3}
\end{equation*}
$$

Thus, we have,

$$
\begin{equation*}
16+8=3 * 2^{3}=\frac{6}{2} * 2^{3}=32 \tag{5.4}
\end{equation*}
$$

From (5.1) and (5.3), we have

$$
\begin{equation*}
\left|W_{A A}\right|+\left|W_{A B}\right|=\left|W_{A B}\right|+\left|W_{B B}\right| \tag{5.5}
\end{equation*}
$$

and it follows that

$$
\left|W_{A A}\right|=\left|W_{B B}\right| .
$$

We can see that these equalities hold for our example.

To finish the proof of Lemma 5.2, we can see that each 3 -walk in $W_{A A}$ corresponds to exactly one $(v, w, 3)$ A-patch, and each 3 -walk in $W_{B B}$ corresponds to exactly one ( $v, w, 3$ ) B-patch.

The validity of the following corollary is a result of $W_{A A}$ and $W_{B B}$ having the same cardinality.

Corollary 5.4. Let $v$ and $w$ be vertices in $V_{1}$ and $k$ a non-negative integer. Let $\mathcal{P}_{(v, w, k)}^{A}$ be the set of $(v, w, k)$ A-patches from $v$ to $w$ and $\mathcal{P}_{(v, w, k)}^{B}$ be the set of $(v, w, k) B$-patches from $v$ to $w$. Then there is a one-to-one correspondence

$$
\mathcal{P}_{(v, w, k)}^{A} \leftrightarrow \mathcal{P}_{(v, w, k)}^{B} .
$$

We can now show that $\Gamma_{A}$ and $\Gamma_{B}$ of a Seidel pair are length isospectral.

Theorem 5.5. Let $k$ be a non-negative integer and $\left(G_{1}, G_{2}, \mathcal{E}\right)$ a Seidel pair. There is a one-to-one correspondence between the set of all closed $k$-walks in $\Gamma_{A}$ and the set of all closed $k$-walks in $\Gamma_{B}$.

We divide every closed $k$-walk $W$ in $\Gamma_{A}$, recall Figure 6.5, into the following three types:

- Type I: $W$ is contained in $G_{1}$
- Type II: $W$ is contained in $G_{2}$
- Type III: $W$ contains some edges in $\mathcal{E}$.

We do the same for all closed $k$-walks $Z$ in $\Gamma_{B}$, recall Figure 6.6:

- Type I': $Z$ is contained in $G_{1}$
- Type $\mathrm{II}^{\prime}: Z$ is contained in $G_{2}$
- Type III': $Z$ contains some edges in $\mathcal{E}^{\mathcal{C}}$.

For a comprehensive list of all such walks in our example, see Section A of the Appendix.

For a closed $k$-walk, or 3 -walk, $W$ in $\Gamma_{A}$, if $W$ is Type I or Type II, then it is also a closed $k$-walk, or 3 -walk, of Type $\mathrm{I}^{\prime}$ or Type $\mathrm{II}^{\prime}$ in $\Gamma_{B}$. Thus we have a correspondence for these walks via the identity mapping.

The completion of the proof requires the construction of a bijection from Type III closed $k$-walks in $\Gamma_{A}$ to Type III' closed $k$-walks in $\Gamma_{B}$. Let

$$
W=\epsilon_{1} \epsilon_{2} \ldots \epsilon_{k}
$$

be a Type III closed $k$-walk in $\Gamma_{A}$. For our example, we have

$$
W=\epsilon_{1} \epsilon_{2} \epsilon_{3}
$$

Consider

$$
W=\{3,1\},\{1,7\},\{7,3\} .
$$

Since $W$ is closed and contains some edge in $\mathcal{E}$, it contains some edge $\epsilon_{m}$ in $\mathcal{E}$ that goes from a vertex in $V_{1}$ to a vertex in $V_{2}$. By permuting the edges in $W$, we obtain

$$
\bar{W}=\epsilon_{m} \epsilon_{m+1} \epsilon_{m+2} \ldots \epsilon_{m+k-1}
$$

where we read the subscripts modulo $k$. This is a closed $k$-walk beginning and ending at some vertex $v$ in $V_{1}$. For our example, we have

$$
\bar{W}=\epsilon_{m} \epsilon_{m+1} \epsilon_{m+2}
$$

and

$$
\bar{W}=\{1,7\},\{7,3\},\{3,1\},
$$

a closed 3 -walk beginning and ending at vertex 1 .

We can view $\bar{W}$ as the following sequence:

$$
\bar{W}=P_{1} W_{1} P_{2} W_{2} \ldots P_{j} W_{j}
$$

where each $P_{i}$ is a $\left(v_{i}, w_{i}, l_{i}\right) A$-patch and each $W_{i}$ is a walk in $G_{1}$ from $w_{i}$ to $v_{i+1}$, with subscripts modulo $j$. For our example, we have

$$
\bar{W}=P_{1} W_{1}
$$

such that

$$
P_{1}=(1,3,2) A \text {-patch passing through vertex } 7 \text { in } \Gamma_{A}
$$

and

$$
W_{1}=\text { a walk of length } 1 \text { from vertex } 3 \text { to } 1 .
$$

By Corollary 5.4, we have a $\left(v_{i}, w_{i}, l_{i}\right)$ B-patch $P_{i}^{\prime}$ that corresponds to each $P_{i}$ patch. Thus, we can replace each $P_{i}$ in $\bar{W}$ with its corresponding $P_{i}^{\prime}$ to get a new walk

$$
\bar{W}^{\prime}=P_{1}^{\prime} W_{1} P_{2}^{\prime} W_{2} \ldots P_{j}^{\prime} W_{j} .
$$

For our example, we have

$$
P_{1}^{\prime}=(1,3,2) \text { B-patch passing through vertex } 11 \text { in } \Gamma_{B}
$$

and

$$
\bar{W}^{\prime}=P_{1}^{\prime} W_{1} .
$$

We now have a closed $k$-walk, or 3 -walk, beginning and ending at $v=$ vertex 1 . However, each $\epsilon_{h}$ of $\bar{W}$ contained in $\mathcal{E}$ has been replaced by $\epsilon_{h}^{\prime}$ in $\mathcal{E}^{\mathcal{C}}$. Therefore, $\bar{W}$ is a closed $k$-walk in $\Gamma_{B}$. To complete this mapping, we take

$$
\bar{W}^{\prime}=\epsilon_{m}^{\prime} \epsilon_{m+1}^{\prime} \epsilon_{m+2}^{\prime} \cdots \epsilon_{m+k-1}^{\prime}
$$

such that each $\epsilon_{h}^{\prime}=\epsilon_{h}$ or its corresponding edge in some $P_{i}^{\prime}$. Thus, we have

$$
\bar{W}^{\prime}=\epsilon_{m}^{\prime} \epsilon_{m+1}^{\prime} \epsilon_{m+2}^{\prime}
$$

such that $\epsilon_{m}^{\prime}=\{1,11\}, \epsilon_{m+1}^{\prime}=\{11,3\}$, and $\epsilon_{m+2}^{\prime}=\{3,1\}=\epsilon_{m+2}$.

We obtain a Type III' closed 3-walk in $\Gamma_{B}$ by applying another cyclic permutation to the edges in $\bar{W}$

$$
\begin{gathered}
W^{\prime}=\epsilon_{1}^{\prime} \epsilon_{2}^{\prime} \ldots \epsilon_{k}^{\prime} \\
W^{\prime}=\epsilon_{1}^{\prime} \epsilon_{2}^{\prime} \epsilon_{3}^{\prime} \\
W^{\prime}=\{3,1\},\{1,11\},\{11,3\}
\end{gathered}
$$

We may invert this mapping $W \mapsto W^{\prime}$ as follows: a closed 3-walk $W^{\prime}$ in $\Gamma_{B}$ contains some first edge $\epsilon_{m}^{\prime}$ in $\mathcal{E}$ from $V_{1}$ to $V_{2}$.

$$
W^{\prime}=\{3,1\},\{1,11\},\{11,3\}
$$

such that $\epsilon_{m}^{\prime}=\{1,11\}$ in $\mathcal{E}^{\mathcal{C}}$ from vertex 1 of $G_{1}$ to vertex 11 of $G_{2}$. We then apply a cyclic permutation to the edges in $W^{\prime}$ such that $\epsilon_{m}^{\prime}$ is first

$$
\bar{W}^{\prime}=\{1,11\},\{11,3\},\{3,1\}
$$

and replace each $\left(v_{i}, w_{i}, l_{i}\right)$ B-patch with its corresponding A-patch which is known to exist by Corollary 5.4.

$$
P_{1}^{\prime}=(1,3,2) A \text {-patch through vertex } 11
$$

$$
P_{1}^{\prime}=(1,3,2) B \text {-patch through vertex } 7 \text {. }
$$

Undoing the cyclic permutation so that the image of $\epsilon_{1}^{\prime}$ is first is our last step

$$
W=\{3,1\},\{1,7\},\{7,3\} .
$$

We may verify this by observing the following of our example:

- The first edge in $W$ from $V_{1}$ to $V_{2}$ is in the same position as the first edge in $W^{\prime}$ from $V_{1}$ to $V_{2}$.
- Replacing a B-patch with an A-patch is the inverse of replacing an Apatch with a B-patch.


## 6 Seidel switching and regularity

We shall now look at Seidel switching with a further restriction on the construction. This is done because, although one might intuitively think the opposite is true, cospectral non-isomorphic pairs of regular graphs appear to be rarer than cospectral pairs of non-regular graphs. Thus we look at Seidel switching under the following restrictions for a regular Seidel pair provided in [7] p. 14 .

Theorem 6.1. Suppose $\left(G_{1}, G_{2}, \mathcal{E}\right)$ is a Seidel pair, and that $\Gamma_{A}$ is $q$-regular. Then

1. $\left|V_{1}\right|$ is even.
2. $G_{1}$ is regular.
3. $\frac{\left|V_{1}\right|}{2}+r=\frac{\left|V_{2}\right|}{2}+s=q$, where $r$ is the valency of $G_{2}$ and $s$ is the valency of $G_{1}$.
4. $\Gamma_{B}$ is $q$-regular.

We begin by providing an example of a regular construction. Figures 6.1-6.3 on p.33a show $G_{1}, G_{2}$, and a pair of isomorphic $\Gamma_{A}$ and $\Gamma_{B}$ that fit the conditions of Theorem 6.1. One can refer back to this example while working through


Figure 6.1


Figure 6.2: $G_{1}$ and $G_{2}$ with $\varepsilon$ and $\varepsilon^{c}$


Figure $6.3: \Gamma_{A}, \Gamma_{B}$ regular
the following proof. A proof of Theorem 6.1 similar to the following can be found in [7].

Proof. As in all cases of Seidel switching, $G_{2}$ is $r$-regular, so in $\Gamma_{A}$ each vertex from $V_{2}$ will be an endpoint of the same number of edges in $\mathcal{E}$. This number will be $\frac{|\mathcal{E}|}{\left|V_{2}\right|}$. This is because in $\mathcal{E}$ edges will be distributed evenly for all $v_{i} \in V_{2}$. Using the previously described method of Seidel construction, we know that

$$
|\mathcal{E}|=\left|V_{1}\right| \times \frac{\left|V_{2}\right|}{2}=\frac{\left|V_{1}\right| \times\left|V_{2}\right|}{2}
$$

So, the number of edges in $\mathcal{E}$ at each vertex in $G_{2}$ will be $\frac{\left|V_{1}\right|}{2}$. This indicates that $\left|V_{1}\right|$ must be even and

$$
\begin{equation*}
q=r+\frac{\left|V_{1}\right|}{2} \tag{6.1}
\end{equation*}
$$

We now consider a vertex $v$ of $G_{1}$ with a valency of $s$. After constructing $\Gamma_{A}$ there are $\frac{\left|V_{2}\right|}{2}$ new edges adjacent to $v$. This follows from the reasoning used above for $G_{2}$. Thus, the valency of $v$ as a vertex of $\Gamma_{A}$ is

$$
s+\frac{\left|V_{2}\right|}{2}
$$

We know that $\Gamma_{A}$ is $q$-regular. So, we can see that

$$
s=q-\frac{\left|V_{2}\right|}{2}
$$

for each choice of $v$. Thus, we have that $G_{1}$ is regular and

$$
\begin{equation*}
q=s+\frac{\left|V_{2}\right|}{2} \tag{6.2}
\end{equation*}
$$

With this we have proved the third part of Theorem 6.1 in (6.1) and (6.2).

We now use a similar argument to prove that $\Gamma_{B}$ is $q$-regular.

Using the fact that $\mathcal{E}^{\mathcal{C}}$ is made up of edges that join each vertex of the graph $G_{1}$ to exactly half of the vertices of the graph $G_{2}$, it is clear that the valency of each vertex in the set $V_{1}$ in the graph $\Gamma_{B}$ is

$$
s+\frac{\left|V_{2}\right|}{2}=q .
$$

Now let $v$ be a vertex of $G_{2}$. We have $\frac{\left|V_{1}\right|}{2}$ vertices in $V_{1}$ that are adjacent to $v$ via edges in $\mathcal{E}$. Thus, there are also $\frac{\left|V_{1}\right|}{2}$ vertices in $V_{1}$ that are not adjacent to $v$ via edges in $\mathcal{E}$. These vertices make up the set of vertices that will be connected to $v$ by edges in the set $\mathcal{E}^{\mathcal{C}}$. Therefore, the valency of a vertex $v$ in the graph $\Gamma_{B}$ is

$$
r+\frac{\left|V_{1}\right|}{2}=q .
$$

Definition 6.2. When all of the conditions of Theorem 6.1 are met, we will refer to $\left(G_{1}, G_{2}, \mathcal{E}\right)$ as a regular Seidel pair.

In [7], Quenell indicates without example that conditions 1,2 and 3 of Theorem 6.1 are not sufficient for the regularity of $\Gamma_{A}$ and $\Gamma_{B}$. Here we provide an example illustrating this insufficiency. Figure 6.4 on p.35a gives $G_{1}$ and $G_{2}$

$$
\begin{aligned}
& 1 \\
& 2 \\
& 4 \\
& 4 \\
& 4 \\
& G_{1} \\
& \text { Figure } 6.4
\end{aligned}
$$



Figure 6.5: Insufficiency of conditions $1,2,3$ of Theorem 6.1
such that $G_{1}$ has an even number of vertices, 6 , and is 1 -regular. We also see that $\frac{\left|V_{1}\right|}{2}+r=3+2=5$ and $\frac{\left|V_{2}\right|}{2}+s=4+1=5$, thus satisfying conditions 1,2, and 3 of Theorem 6.1. However, once we add $\mathcal{E}$ as shown in Figure 6.5 on p.35a, we generate $\Gamma_{A}$ and $\Gamma_{B}$ that are non-regular. To see this, compare vertices 1, 7, and 10 . We note that there do exist $\mathcal{E}$ that would induce regularity, but it is not guaranteed that such a $\mathcal{E}$ will be chosen.

Corollary 6.3. When the conditions of Theorem 6.1 are met, $\left|V_{1}\right|=\left|V_{2}\right|$ if and only if $r=s$.

Proof. Consider

$$
\frac{\left|V_{1}\right|}{2}+r=\frac{\left|V_{2}\right|}{2}+s
$$

Then we have

$$
\begin{aligned}
&\left|V_{1}\right|=\left|V_{2}\right| \\
& \Leftrightarrow \\
& \frac{\left|V_{1}\right|}{2}+r=\frac{\left|V_{1}\right|}{2}+s \\
& \Leftrightarrow \\
& r=s
\end{aligned}
$$

Corollary 6.4. If $\left(G_{1}, G_{2}, \mathcal{E}\right)$ is a Seidel pair in which either $G_{1}$ or $G_{2}$ contains only two vertices, then $\Gamma_{A}$ is isomorphic to $\Gamma_{B}$.

Quenell indicates in [7], without proof, that using the above and "a little more work", the following can be shown using the idea that $G_{1}$ must be the union of two $K_{2} s$ and the automorphism group of $G_{1}$ is large enough to induce an isomorphism between $\Gamma_{A}$ and $\Gamma_{B}$ for any choice of $\mathcal{E}$.

Corollary 6.5. If $\left|V_{1}\right|=\left|V_{2}\right|=4$ and $G_{1}$ is 1-regular, then the graphs $\Gamma_{A}$ and $\Gamma_{B}$ in any Seidel pair $\left(G_{1}, G_{2}, \mathcal{E}\right)$ are isomorphic.

We are able to give a proof as follows:

Proof. Corollary 5.2 implies that $G_{2}$ must also be 1-regular.

We now look to give a concrete proof. We first notice that Theorem 5.1, Corollary 5.2 and our hypothesis imply that $G_{2}$ must also be the union of two $K_{2} s$. See Figure 6.6 on p.37a.

We provide four different choices of $\mathcal{E}$ and consider the mapping of vertices in $V_{A}$ to vertices in $V_{B}$. Figures 6.7-6.18 on pp.37a-d show us $G_{1}$ and $G_{2}$ as well as these four different examples of $\mathcal{E}$ that generate pairs of isomorphic graphs. Note the differences in location of vertices 1, 2, 3, and 4 in each $\Gamma_{A}$ and $\Gamma_{B}$.

We determine the automorphism group of $G_{1}$ as follows:

- $\sigma_{0}: 1234$
- $\sigma_{1}: 1243$


Figure 6.6


Figure 6.7: $G_{1}$ and $G_{2}$ with first choice of $\varepsilon$


Figure 6.8: $\Gamma_{A}$ for first choice of $\varepsilon$


Figure $6.9: \Gamma_{B}$ for first choice of $\varepsilon$


Figure $6.10: G_{1}$ and $G_{2}$ with second choice of $\varepsilon$


Figure 6.11: $\Gamma_{A}^{\prime}$ for second choice of $\varepsilon$


Figure $6.12: \Gamma_{B}$ for second choice of $\varepsilon$


Figure $6.13: G_{1}$ and $G_{2}$ with third choice of $\varepsilon$


Figure 6. $14: \Gamma_{A}$ for third choice of $\varepsilon$

$\Gamma_{\beta}$
Figure $6.15: \Gamma_{B}$ for third choice of $\varepsilon$


Figure G.16: $G_{1}$ and $G_{2}$ with fourth choice of $\varepsilon$


Figure 6.17: $\Gamma_{\text {A for fourth choice of } \varepsilon} \varepsilon$


Figure 6.18: $\Gamma_{B}$ for four th choice of $\varepsilon$

- $\sigma_{2}: 2134$
- $\sigma_{3}: 2143$
- $\sigma_{4}: 3421$
- $\sigma_{5}: 3412$
- $\sigma_{6}: 4312$
- $\sigma_{7}: 4321$

Thus,

$$
\operatorname{Aut}\left(G_{1}\right)=\{1,(12),(34),(12)(34),(13)(24),(1324),(1423),(14)(23)\}
$$

This is $D_{4}$, a subgroup of $S_{4}$, corresponding to the symmetries of the square as shown in Figure 6.20 on p.38a.

We represent the vertices of $G_{1}$ as the vertices of a square, as shown in Figure 6.19 on p.38a. We have two adjacent pairs corresponding to two diagonals of the square and four non-adjacent pairs corresponding to the four sides of the square.

We note that $\operatorname{Aut}\left(G_{1}\right)$ is transitive on the two adjacent pairs and the four nonadjacent pairs. In fact, the following is clear:

Proposition 6.6. For vertices $\{a, b, c, d\}$ of $G_{1}$,


Figure 6.19


Figure 6.20: Ant $\left(G_{1}\right)$ is the symmetries of the square, $\mathrm{O}_{4}$.

1. If $a$ and $d$ are adjacent and $b$ and $c$ are adjacent in $G_{1}$, then $(a d)(b c) \in$ $\operatorname{Aut}\left(G_{1}\right)$.
2. If $a$ and $d$ are nonadjacent and $b$ and $c$ are nonadjacent in $G_{1}$, then $(a d)(b c) \in \operatorname{Aut}\left(G_{1}\right)$.

Given $G_{1}$ and $G_{2}$ as shown and labeled earlier, we let

$$
\begin{aligned}
& \text { vertices of } G_{1}=\{1,2,3,4\}=\{a, b, c, d\} \\
& \text { vertices of } G_{2}=\{5,6,7,8\}=\{r, s, t, u\}
\end{aligned}
$$

and think of the choice of $\mathcal{E}$ as a map

$$
\phi:\{1,2,3,4\} \rightarrow \operatorname{pairs}\{56,57,58,67,68,78\}
$$

and $\mathcal{E}^{\mathcal{C}} \leftrightarrow \phi^{C}$.

We can divide these mappings into two cases, $\left|\phi^{-1}\{r, s\}\right|=2$ for some pair $\{r, s\}$ and $\left|\phi^{-1}\{r, s\}\right| \leq 1$ for all pairs $\{r, s\}$.

Case 1: $\left|\phi^{-1}\{r, s\}\right|=2$ for some pair $\{r, s\}$. This forces the following:

$$
\begin{array}{ccc}
\phi & \Gamma_{A} & \Gamma_{B} \\
\phi(a)=\{r, s\} & \text { ar,as } \in \mathcal{E} & \text { at, au } \in \mathcal{E}^{\mathcal{C}} \\
\phi(b)=\{r, s\} & \text { br,bs } \in \mathcal{E} & \text { bt,bu } \mathcal{E}^{\mathcal{C}} \\
\phi(c)=\{t, u\} & \mathrm{ct}, \mathrm{cu} \in \mathcal{E} & \mathrm{cr}, \mathrm{cs} \in \mathcal{E}^{\mathcal{C}} \\
\phi(d)=\{t, u\} & \mathrm{dt}, \mathrm{du} \in \mathcal{E} & \mathrm{dr}, \mathrm{ds} \in \mathcal{E}^{\mathcal{C}}
\end{array}
$$

If $a$ and $b$ are adjacent, then $c$ and $d$ are also adjacent and if $a$ and $b$ are nonadjacent, then $c$ and $d$ are also nonadjacent. We can say that there exists $\sigma \in \operatorname{Aut}\left(G_{1}\right)$ such that $\sigma\{a, b\}=\{c, d\}$. This $\sigma$ induces $\Gamma_{A} \simeq \Gamma_{B}$.

Case 2: $\left|\phi^{-1}\{r, s\}\right| \leq 1$ for all pairs $\{r, s\}$.
Suppose

$$
\phi(a)=\{r, s\} .
$$

Then,

$$
\begin{aligned}
& \phi(b)=\{r, t\} \\
& \phi(c)=\{s, u\} \\
& \phi(d)=\{t, u\}
\end{aligned}
$$

because $r$ and $s$ cannot occur together again, so $t$ and $u$ must occur in combination with $r$ and $s$ in some order. Thus, we have the following:

$$
\begin{array}{cc}
\Gamma_{A} & \Gamma_{B} \\
\text { ar,as } \in \mathcal{E} & \mathrm{at}, \mathrm{au} \in \mathcal{E}^{\mathcal{C}} \\
\mathrm{br}, \mathrm{bt} \in \mathcal{E} & \mathrm{bs}, \mathrm{bu} \in \mathcal{E}^{\mathcal{C}} \\
\mathrm{cs}, \mathrm{cu} \in \mathcal{E} & \mathrm{cr}, \mathrm{ct} \in \mathcal{E}^{\mathcal{C}} \\
\mathrm{dt}, \mathrm{du} \in \mathcal{E} & \mathrm{dr}, \mathrm{ds} \in \mathcal{E}^{\mathcal{C}}
\end{array}
$$

We look at Figures 6.21 and 6.22 on p.40a to see the differences in $\mathcal{E}$ and $\mathcal{E}^{\mathcal{C}}$.

Claim: $\sigma=(a d)(b c) \in \operatorname{Aut}\left(G_{1}\right)$ induces $\Gamma_{A} \simeq \Gamma_{B}$.
Case A: If $a$ and $d$ are adjacent then $b$ and $c$ are adjacent. This can be seen in Figure 6.23 on p.40b.


Figure 6.21: \& for case 2


Figure $0.22: \varepsilon^{c}$ for case 2


Figure 6.2.3: Case A


Figure 6.24: Possibility (i) of case $B$


Figure 6.25: Possibility (ii) of case B

Case B: If $a$ and $d$ are nonadjacent then $b$ and $c$ are nonadjacent. There are two possibilities for this case, as shown in Figures 6.24 and 6.25 on p.40b.

After looking at various examples of Seidel pairs for different combinations of $G_{1}$ and $G_{2}$, the following conjecture emerged.

Conjecture: If $G_{1}, G_{2}$ are both regular and $\left|V_{1}\right|$ and $\left|V_{2}\right|$ are both even, then $\Gamma_{A}$ and $\Gamma_{B}$ will both be regular.

We look to Figures 6.26-6.28 on p.41a for an example illustrating the ideas of this conjecture.

There are, however, a few questions that arise from this conjecture:

1. Do $G_{1}$ and $G_{2}$ both need to have the same number of vertices?
2. Do $G_{1}$ and $G_{2}$ need to have the same valency?

We now attempt to answer these questions in an effort to support the conjecture and determine if it is indeed true.

1. The example shown in Figures 6.29 and 6.30 on p.41b shows that when $G_{1}$ and $G_{2}$ have a different number of vertices, our conjecture does not hold. This is clear from comparing the degrees of vertices 4 and 10 . This counterexample shows us that the original conjecture is false, indicating a need for further



5

$$
3
$$

$G_{1}$
Figure 6.26: $G_{1}$, and $G_{2}$


Figure $0.27: G_{1}$ and $G_{2}$ with $\varepsilon$

figure $6.28: \Gamma_{A}$ for general example of conjecture

$G_{1}$


Figure 6.29


Figure 6.30: $G_{1}$ and $G_{2}$ with E for condition !
restriction on the hypothesis. Thus, we now provide a revised version of the conjecture to account for what we have just learned:

Conjecture (Revised): If $G_{1}, G_{2}$ are both regular and $\left|V_{1}\right|=\left|V_{2}\right|=2 N$, then $\Gamma_{A}, \Gamma_{B}$ will both be regular.
2. Figures 6.31-6.33 on p.42a give us a pair of $G_{1}$ and $G_{2}$ with different valencies. This indicates to us that the second condition we are questioning is not necessary. We have been able to prove a special case of the conjecture and also show that the resulting $\Gamma_{A}$ and $\Gamma_{B}$ are cospectral. The following theorem illustrates an example of the conjecture with the two mentioned possible restrictions.

Theorem 6.7. Given $q$-regular $G_{1}$ and $G_{2}$ such that

$$
\left|V_{1}\right|=\left|V_{2}\right|=2 N .
$$

Then

1. $\Gamma_{A}$ and $\Gamma_{B}$ are $(q+N)$-regular.
2. $\Gamma_{A}$ and $\Gamma_{B}$ are cospectral.

Proof. Here we provide the proof of (1).
We are given the following:


Figure 6.31


Figure 6.32: $G_{1}$ and $\epsilon_{2}$ with $\varepsilon$


Figure 6.33: $\Gamma_{A}$ for condition 2

$$
\begin{gathered}
\left|V_{1}\right|=\left|V_{2}\right|=2 N \\
\Gamma_{A}=\left(V_{A}, E_{A}\right)=\left(V_{1} \cup V_{2}, E_{1} \cup E_{2} \cup \mathcal{E}\right) \\
\Gamma_{B}=\left(V_{B}, E_{B}\right)=\left(V_{1} \cup V_{2}, E_{1} \cup E_{2} \cup \mathcal{E}^{\mathcal{C}}\right) \\
\left|V_{A}\right|=\left|V_{B}\right|=4 N \\
|\mathcal{E}|=\left|\mathcal{E}^{\mathcal{C}}\right|
\end{gathered}
$$

Since $\mathcal{E}$ is a set of edges connecting half of the vertices in $G_{1}$ to every vertex in $G_{2}$, we are adding $N$ edges to each vertex upon construction of $\Gamma_{A}$. The same occurs with the construction of $\Gamma_{B}$ using $\mathcal{E}^{\mathcal{C}}$. Given that $G_{1}$ and $G_{2}$ are $q$-regular, we can now see that $\Gamma_{A}$ and $\Gamma_{B}$ are $(q+N)$-regular.

We refer you to section 5 for an illustrated example that works through the proof provided in [7] of the fact that $\Gamma_{A}$ and $\Gamma_{B}$ will be cospectral for any Seidel switch; this is a special case.

This is also a special case of the regular Seidel pair described in Theorem 6.1.

## 7 Seidel switching and the Ihara zeta function

We now return to the Ihara zeta function defined earlier and discuss a connection between Seidel switching and two graphs with equal Ihara zeta functions.

Ihara defined the zeta function as a product over p-adic group elements. It was not until Serre looked at the product that the Ihara zeta function had a graph theoretic interpretation. Sunada, Hashimoto, Bass and others extended the theory.

Through the following theorem, Aubi Mellien was able to show a direct connection between the equality of Ihara zeta functions of two graphs and their cospectrality. Mellien, a student participating in the mathematics REU at LSU during the summer of 2001, developed this theorem while working with Robert Perlis.

Theorem 7.1. Aubi's Theorem: Let $\Gamma, \Gamma^{\prime}$ be regular md2 graphs. Then $Z_{\Gamma}(u)=Z_{\Gamma^{\prime}}(u)$ if and only if $\Gamma$ and $\Gamma^{\prime}$ are cospectral.

A proof of Aubi's Theorem can be found on pp.22-24 of [2] and is referred to as Theorem 3.1.2.

The next theorem follows from Aubi's Theorem, as stated above, and the proven fact that $\Gamma_{A}$ and $\Gamma_{B}$ are cospectral (Theorem 5.1).

Theorem 7.2. For $q$-regular graphs $G_{1}$ and $G_{2}$ such that $q \geq 1, Z_{\Gamma_{A}}(u)=$ $Z_{\Gamma_{B}}(u)$ where $\left(\Gamma_{A}, \Gamma_{B}\right)$ is any Seidel switch of $G_{1}, G_{2}$.

## 8 Small, regular Seidel pairs

One aspect of interest in regards to Seidel switching is the construction of regular Seidel pairs such that $\Gamma_{A}$ and $\Gamma_{B}$ are non-isomorphic. It is of particular interest to look at small examples. From [7],

Lemma 8.1. There exist at least three regular Seidel pairs with $\Gamma_{A}$ not isomorphic to $\Gamma_{B}$ in which

$$
\left|V_{1}\right|=\left|V_{2}\right|=4
$$

and $G_{1}$ and $G_{2}$ are both 2-regular.

In [7] (p.17), Quenell provides one example of such a Seidel pair. Here we provide two more examples of Seidel pairs of this type.

Figures 8.1-8.3 on p.45a show us the Seidel pair given in [7]. Figures 8.4-8.9 on p.45b-c then provide the two more non-isomorphic Seidel pairs we have found such that the described conditions have been met.

Thus we can now see that there are at least three regular Seidel pairs of this type.

$\Theta_{1}$

Figure 8.1 (exampl el)


Figure 8.2: $\theta_{1}$ and $G_{2}$ with $\varepsilon$ (example 1)

$\Gamma_{B}$
Figure 8.3: First example of Lemma 8.1 [6]


Figure 8.5: $G_{1}$ and $G_{2}$ with $\varepsilon$ (example 2)


Figure 8.6: second example of Lemma 8.1
6

3

$\int_{8}^{7}$
$G$
$G_{2}$
Figure 8.7 (exarnple 3)


Figure $8.8: G_{1}$ and $G_{2}$ with $\varepsilon$ (example 3 )


Figure 8.9 : third example of Lemma 8.1

## 9 Further questions

While exploring the preceding results, many other questions have come up that would be of interest to pursue. We provide some of these questions below:

- Is there a way to compute the number of possible edge sets that exist when given $G_{1}$ and $G_{2}$ ? (Excluding redundancy of isomorphisms)
- Do there exist more generalizations of examples we have referred to?
- Are there any consistent results when $G_{1}=G_{2}$ ?
- Can you determine when $\Gamma_{A}$ and $\Gamma_{B}$ will be isomorphic?
- Are there any general results when $G_{1}$ has an odd number of vertices and is not regular?
- What happens when $G_{1}$ and $G_{2}$ both have an even number or vertices, but $G_{1}$ is not regular?
- What happens when $G_{1}$ is regular and has an odd number of vertices?
- Are there any general results when $G_{1}$ and $G_{2}$ have the same regularity versus different regularity?
- How often do symmetric Seidel pairs arise?
- What affects do the presence of loops in $G_{1}$ and/or $G_{2}$ have on $\Gamma_{A}$ and $\Gamma_{B} ?$
- Why is it that cospectral pairs of regular graphs are rarer than cospectral pairs of non-regular graphs?


## A All 3-walks in $\Gamma_{A}$ and $\Gamma_{B}$ (Combinatorial Proof)

We provide a comprehensive list of all closed 3-walks $W$ and $Z$ in $\Gamma_{A}$ and $\Gamma_{B}$ respectively such that they are divided into the three types as described.

Type I: all closed 3-walks such that $W$ is contained in $G_{1}$. There will be none containing vertices 4 or 5 .

- $1 \rightarrow 2 \rightarrow(a) 3 \rightarrow 1$
- $1 \rightarrow 2 \rightarrow(b) 3 \rightarrow 1$
- $1 \rightarrow 3 \rightarrow(a) 2 \rightarrow 1$
- $1 \rightarrow 3 \rightarrow(b) 2 \rightarrow 1$
- $2 \rightarrow 1 \rightarrow 3 \rightarrow(a) 2$
- $2 \rightarrow 1 \rightarrow 3 \rightarrow(b) 2$
- $2 \rightarrow(a) 3 \rightarrow 1 \rightarrow 2$
- $2 \rightarrow(b) 3 \rightarrow 1 \rightarrow 2$
- $3 \rightarrow 1 \rightarrow 2 \rightarrow(a) 3$
- $3 \rightarrow 1 \rightarrow 2 \rightarrow(b) 3$
- $3 \rightarrow(a) 2 \rightarrow 1 \rightarrow 3$
- $3 \rightarrow(b) 2 \rightarrow 1 \rightarrow 3$
$\mid$ Type $\mathrm{I} W \mid=12$

Type II: all closed 3 -walks $W$ in $G_{2}$. These will contain vertices 6,7 , and 8 or vertex 11, but not vertices 9 or 10 .

- $6 \rightarrow 7 \rightarrow 8 \rightarrow 6$
- $6 \rightarrow 8 \rightarrow 7 \rightarrow 6$
- $7 \rightarrow 6 \rightarrow 8 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 6 \rightarrow 7$
- $8 \rightarrow 6 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 7 \rightarrow 6 \rightarrow 8$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
$\mid$ Type II $W \mid=14$

Type III: $W$ contains some edges in $\mathcal{E}$
Let us divide these up by the vertex at which the 3 -walk begins and end.

Vertex 1:

- $1 \rightarrow 3 \rightarrow 7 \rightarrow 1$
- $1 \rightarrow 3 \rightarrow 8 \rightarrow 1$
- $1 \rightarrow 6 \rightarrow 7 \rightarrow 1$
- $1 \rightarrow 6 \rightarrow 8 \rightarrow 1$
- $1 \rightarrow 7 \rightarrow 3 \rightarrow 1$
- $1 \rightarrow 7 \rightarrow 6 \rightarrow 1$
- $1 \rightarrow 7 \rightarrow 8 \rightarrow 1$
- $1 \rightarrow 8 \rightarrow 3 \rightarrow 1$
- $1 \rightarrow 8 \rightarrow 6 \rightarrow 1$
- $1 \rightarrow 8 \rightarrow 7 \rightarrow 1$

Vertex 2:

- $2 \rightarrow(a) 3 \rightarrow 9 \rightarrow 2$
- $2 \rightarrow(b) 3 \rightarrow 9 \rightarrow 2$
- $2 \rightarrow 9 \rightarrow 3 \rightarrow(a) 2$
- $2 \rightarrow 9 \rightarrow 3 \rightarrow(b) 2$
- $2 \rightarrow 9 \rightarrow(a) 10 \rightarrow 2$
- $2 \rightarrow 9 \rightarrow(b) 10 \rightarrow 2$
- $2 \rightarrow 10 \rightarrow(a) 9 \rightarrow 2$
- $2 \rightarrow 10 \rightarrow(b) 9 \rightarrow 2$
- $2 \rightarrow 11 \rightarrow(c w) 11 \rightarrow 2$
- $2 \rightarrow 11 \rightarrow(c c w) 11 \rightarrow 2$

Vertex 3:

- $3 \rightarrow 1 \rightarrow 7 \rightarrow 3$
- $3 \rightarrow 1 \rightarrow 8 \rightarrow 3$
- $3 \rightarrow(a) 2 \rightarrow 9 \rightarrow 3$
- $3 \rightarrow(b) 2 \rightarrow 9 \rightarrow 3$
- $3 \rightarrow 7 \rightarrow 1 \rightarrow 3$
- $3 \rightarrow 7 \rightarrow 8 \rightarrow 3$
- $3 \rightarrow 8 \rightarrow 1 \rightarrow 3$
- $3 \rightarrow 8 \rightarrow 7 \rightarrow 3$
- $3 \rightarrow 9 \rightarrow 2 \rightarrow(a) 3$
- $3 \rightarrow 9 \rightarrow 2 \rightarrow(b) 3$

Vertex 4:

- $4 \rightarrow(a) 5 \rightarrow 9 \rightarrow 4$
- $4 \rightarrow(a) 5 \rightarrow 10 \rightarrow 4$
- $4 \rightarrow(b) 5 \rightarrow 9 \rightarrow 4$
- $4 \rightarrow(b) 5 \rightarrow 10 \rightarrow 4$
- $4 \rightarrow 9 \rightarrow 5 \rightarrow(a) 4$
- $4 \rightarrow 9 \rightarrow 5 \rightarrow(b) 4$
- $4 \rightarrow 9 \rightarrow(a) 10 \rightarrow 4$
- $4 \rightarrow 9 \rightarrow(b) 10 \rightarrow 4$
- $4 \rightarrow 10 \rightarrow 5 \rightarrow(a) 4$
- $4 \rightarrow 10 \rightarrow 5 \rightarrow(b) 4$
- $4 \rightarrow 10 \rightarrow(a) 9 \rightarrow 4$
- $4 \rightarrow 10 \rightarrow(b) 9 \rightarrow 4$

Vertex 5:

- $5 \rightarrow(a) 4 \rightarrow 9 \rightarrow 5$
- $5 \rightarrow(a) 4 \rightarrow 10 \rightarrow 5$
- $5 \rightarrow(b) 4 \rightarrow 9 \rightarrow 5$
- $5 \rightarrow(b) 4 \rightarrow 10 \rightarrow 5$
- $5 \rightarrow 9 \rightarrow 4(a) \rightarrow 5$
- $5 \rightarrow 9 \rightarrow 4 \rightarrow(b) 5$
- $5 \rightarrow 9 \rightarrow(a) 10 \rightarrow 5$
- $5 \rightarrow 9 \rightarrow(b) 10 \rightarrow 5$
- $5 \rightarrow 10 \rightarrow 4 \rightarrow(a) 5$
- $5 \rightarrow 10 \rightarrow 4 \rightarrow(b) 5$
- $5 \rightarrow 10 \rightarrow(a) 9 \rightarrow 5$
- $5 \rightarrow 10 \rightarrow(b) 9 \rightarrow 5$
- $5 \rightarrow 11 \rightarrow(c w) 11 \rightarrow 5$
- $5 \rightarrow 11 \rightarrow(c c w) 11 \rightarrow 5$

Vertex 6:

- $6 \rightarrow 1 \rightarrow 7 \rightarrow 6$
- $6 \rightarrow 1 \rightarrow 8 \rightarrow 6$
- $6 \rightarrow 7 \rightarrow 1 \rightarrow 6$
- $6 \rightarrow 8 \rightarrow 1 \rightarrow 6$

Vertex 7:

- $7 \rightarrow 1 \rightarrow 3 \rightarrow 7$
- $7 \rightarrow 1 \rightarrow 6 \rightarrow 7$
- $7 \rightarrow 1 \rightarrow 8 \rightarrow 7$
- $7 \rightarrow 3 \rightarrow 1 \rightarrow 7$
- $7 \rightarrow 3 \rightarrow 8 \rightarrow 7$
- $7 \rightarrow 6 \rightarrow 1 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 1 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 3 \rightarrow 7$

Vertex 8:

- $8 \rightarrow 1 \rightarrow 3 \rightarrow 8$
- $8 \rightarrow 1 \rightarrow 6 \rightarrow 8$
- $8 \rightarrow 1 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 3 \rightarrow 1 \rightarrow 8$
- $8 \rightarrow 3 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 6 \rightarrow 1 \rightarrow 8$
- $8 \rightarrow 7 \rightarrow 1 \rightarrow 8$
- $8 \rightarrow 7 \rightarrow 3 \rightarrow 8$

Vertex 9:

- $9 \rightarrow 2 \rightarrow(a) 3 \rightarrow 9$
- $9 \rightarrow 2 \rightarrow(b) 3 \rightarrow 9$
- $9 \rightarrow 2 \rightarrow 10 \rightarrow(a) 9$
- $9 \rightarrow 2 \rightarrow 10 \rightarrow(b) 9$
- $9 \rightarrow 3 \rightarrow(a) 2 \rightarrow 9$
- $9 \rightarrow 3 \rightarrow(b) 2 \rightarrow 9$
- $9 \rightarrow 4 \rightarrow(a) 5 \rightarrow 9$
- $9 \rightarrow 4 \rightarrow(b) 5 \rightarrow 9$
- $9 \rightarrow 4 \rightarrow 10 \rightarrow(a) 9$
- $9 \rightarrow 4 \rightarrow 10 \rightarrow(b) 9$
- $9 \rightarrow 5 \rightarrow(a) 4 \rightarrow 9$
- $9 \rightarrow 5 \rightarrow(b) 4 \rightarrow 9$
- $9 \rightarrow 5 \rightarrow 10 \rightarrow(a) 9$
- $9 \rightarrow 5 \rightarrow 10 \rightarrow(b) 9$
- $9 \rightarrow(a) 10 \rightarrow 2 \rightarrow 9$
- $9 \rightarrow(a) 10 \rightarrow 4 \rightarrow 9$
- $9 \rightarrow(a) 10 \rightarrow 5 \rightarrow 9$
- $9 \rightarrow(b) 10 \rightarrow 2 \rightarrow 9$
- $9 \rightarrow(b) 10 \rightarrow 4 \rightarrow 9$
- $9 \rightarrow(b) 10 \rightarrow 5 \rightarrow 9$

Vertex 10:

- $10 \rightarrow 2 \rightarrow 9 \rightarrow(a) 10$
- $10 \rightarrow 2 \rightarrow 9 \rightarrow(b) 10$
- $10 \rightarrow 4 \rightarrow(a) 5 \rightarrow 10$
- $10 \rightarrow 4 \rightarrow(b) 5 \rightarrow 10$
- $10 \rightarrow 4 \rightarrow 9 \rightarrow(a) 10$
- $10 \rightarrow 4 \rightarrow 9 \rightarrow(b) 10$
- $10 \rightarrow 5 \rightarrow(a) 4 \rightarrow 10$
- $10 \rightarrow 5 \rightarrow(b) 4 \rightarrow 10$
- $10 \rightarrow 5 \rightarrow 9 \rightarrow(a) 10$
- $10 \rightarrow 5 \rightarrow 9 \rightarrow(b) 10$
- $10 \rightarrow(a) 9 \rightarrow 2 \rightarrow 10$
- $10 \rightarrow(a) 9 \rightarrow 4 \rightarrow 10$
- $10 \rightarrow(a) 9 \rightarrow 5 \rightarrow 10$
- $10 \rightarrow(b) 9 \rightarrow 2 \rightarrow 10$
- $10 \rightarrow(b) 9 \rightarrow 4 \rightarrow 10$
- $10 \rightarrow(b) 9 \rightarrow 5 \rightarrow 10$

Vertex 11:

- $11 \rightarrow 2 \rightarrow 11 \rightarrow(c w) 11$
- $11 \rightarrow 2 \rightarrow 11 \rightarrow(c c w) 11$
- $11 \rightarrow 5 \rightarrow 11 \rightarrow(c w) 11$
- $11 \rightarrow 5 \rightarrow 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow 2 \rightarrow 11$
- $11 \rightarrow(c w) 11 \rightarrow 5 \rightarrow 11$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow 2 \rightarrow 11$
- $11 \rightarrow(c c w) 11 \rightarrow 5 \rightarrow 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
$\mid$ Type III $W \mid=128$

Type I' for 3 -walks $Z$ contained in $G_{1}$ and Type II' 3 -walks $Z$ in $G_{2}$ will be the same as Type I and II $W$ walks respectively. Thus, we now list all of the Type III' 3 -walks $Z$.

Type III': $Z$ is a 3 -walk containing some edges in $\mathcal{E}^{\mathcal{C}}$.

Vertex 1:

- $1 \rightarrow 3 \rightarrow 10 \rightarrow 1$
- $1 \rightarrow 3 \rightarrow 11 \rightarrow 1$
- $1 \rightarrow 9 \rightarrow(a) 10 \rightarrow 1$
- $1 \rightarrow 9 \rightarrow(b) 10 \rightarrow 1$
- $1 \rightarrow 10 \rightarrow 3 \rightarrow 1$
- $1 \rightarrow 10 \rightarrow(a) 9 \rightarrow 1$
- $1 \rightarrow 10 \rightarrow(b) 9 \rightarrow 1$
- $1 \rightarrow 11 \rightarrow 3 \rightarrow 1$
- $1 \rightarrow 11 \rightarrow(c w) 11 \rightarrow 1$
- $1 \rightarrow 11 \rightarrow(c c w) 11 \rightarrow 1$

Vertex 2:

- $2 \rightarrow(a) 3 \rightarrow 6 \rightarrow 2$
- $2 \rightarrow(b) 3 \rightarrow 6 \rightarrow 2$
- $2 \rightarrow 6 \rightarrow 3 \rightarrow(a) 2$
- $2 \rightarrow 6 \rightarrow 3 \rightarrow(b) 2$
- $2 \rightarrow 6 \rightarrow 7 \rightarrow 2$
- $2 \rightarrow 6 \rightarrow 8 \rightarrow 2$
- $2 \rightarrow 7 \rightarrow 6 \rightarrow 2$
- $2 \rightarrow 7 \rightarrow 8 \rightarrow 2$
- $2 \rightarrow 8 \rightarrow 6 \rightarrow 2$
- $2 \rightarrow 8 \rightarrow 7 \rightarrow 2$

Vertex 3:

- $3 \rightarrow 1 \rightarrow 10 \rightarrow 3$
- $3 \rightarrow 1 \rightarrow 11 \rightarrow 3$
- $3 \rightarrow(a) 2 \rightarrow 6 \rightarrow 3$
- $3 \rightarrow(b) 2 \rightarrow 6 \rightarrow 3$
- $3 \rightarrow 6 \rightarrow 2 \rightarrow(a) 3$
- $3 \rightarrow 6 \rightarrow 2 \rightarrow(b) 3$
- $3 \rightarrow 10 \rightarrow 1 \rightarrow 3$
- $3 \rightarrow 11 \rightarrow 1 \rightarrow 3$
- $3 \rightarrow 11 \rightarrow(c w) 11 \rightarrow 3$
- $3 \rightarrow 11 \rightarrow(c c w) 11 \rightarrow 3$

Vertex 4:

- $4 \rightarrow(a) 5 \rightarrow 6 \rightarrow 4$
- $4 \rightarrow(a) 5 \rightarrow 7 \rightarrow 4$
- $4 \rightarrow(b) 5 \rightarrow 6 \rightarrow 4$
- $4 \rightarrow(b) 5 \rightarrow 7 \rightarrow 4$
- $4 \rightarrow 6 \rightarrow 5 \rightarrow(a) 4$
- $4 \rightarrow 6 \rightarrow 5 \rightarrow(b) 4$
- $4 \rightarrow 6 \rightarrow 7 \rightarrow 4$
- $4 \rightarrow 7 \rightarrow 5 \rightarrow(a) 4$
- $4 \rightarrow 7 \rightarrow 5 \rightarrow(b) 4$
- $4 \rightarrow 7 \rightarrow 6 \rightarrow 4$
- $4 \rightarrow 11 \rightarrow(c w) 11 \rightarrow 4$
- $4 \rightarrow 11 \rightarrow(c c w) 11 \rightarrow 4$

Vertex 5:

- $5 \rightarrow(a) 4 \rightarrow 6 \rightarrow 5$
- $5 \rightarrow(a) 4 \rightarrow 7 \rightarrow 5$
- $5 \rightarrow(b) 4 \rightarrow 6 \rightarrow 5$
- $5 \rightarrow(b) 4 \rightarrow 7 \rightarrow 5$
- $5 \rightarrow 6 \rightarrow 4 \rightarrow(a) 5$
- $5 \rightarrow 6 \rightarrow 4 \rightarrow(b) 5$
- $5 \rightarrow 6 \rightarrow 7 \rightarrow 5$
- $5 \rightarrow 6 \rightarrow 8 \rightarrow 5$
- $5 \rightarrow 7 \rightarrow 4 \rightarrow(a) 5$
- $5 \rightarrow 7 \rightarrow 4 \rightarrow(b) 5$
- $5 \rightarrow 7 \rightarrow 6 \rightarrow 5$
- $5 \rightarrow 7 \rightarrow 8 \rightarrow 5$
- $5 \rightarrow 8 \rightarrow 6 \rightarrow(a) 5$
- $5 \rightarrow 8 \rightarrow 6 \rightarrow(b) 5$
- $5 \rightarrow 8 \rightarrow 7 \rightarrow(a) 5$
- $5 \rightarrow 8 \rightarrow 7 \rightarrow(b) 5$

Vertex 6:

- $6 \rightarrow 2 \rightarrow(a) 3 \rightarrow 6$
- $6 \rightarrow 2 \rightarrow(b) 3 \rightarrow 6$
- $6 \rightarrow 2 \rightarrow 7 \rightarrow 6$
- $6 \rightarrow 2 \rightarrow 8 \rightarrow 6$
- $6 \rightarrow 3 \rightarrow(a) 2 \rightarrow 6$
- $6 \rightarrow 3 \rightarrow(b) 2 \rightarrow 6$
- $6 \rightarrow 4 \rightarrow(a) 5 \rightarrow 6$
- $6 \rightarrow 4 \rightarrow(b) 5 \rightarrow 6$
- $6 \rightarrow 4 \rightarrow 7 \rightarrow 6$
- $6 \rightarrow 5 \rightarrow(a) 4 \rightarrow 6$
- $6 \rightarrow 5 \rightarrow(b) 4 \rightarrow 6$
- $6 \rightarrow 5 \rightarrow 7 \rightarrow 6$
- $6 \rightarrow 5 \rightarrow 8 \rightarrow 6$
- $6 \rightarrow 7 \rightarrow 2 \rightarrow 6$
- $6 \rightarrow 7 \rightarrow 4 \rightarrow 6$
- $6 \rightarrow 7 \rightarrow 5 \rightarrow 6$
- $6 \rightarrow 8 \rightarrow 2 \rightarrow 6$
- $6 \rightarrow 8 \rightarrow 5 \rightarrow 6$


## Vertex 7:

- $7 \rightarrow 2 \rightarrow 6 \rightarrow 7$
- $7 \rightarrow 2 \rightarrow 8 \rightarrow 7$
- $7 \rightarrow 4 \rightarrow(a) 5 \rightarrow 7$
- $7 \rightarrow 4 \rightarrow(b) 5 \rightarrow 7$
- $7 \rightarrow 4 \rightarrow 6 \rightarrow 7$
- $7 \rightarrow 5 \rightarrow(a) 4 \rightarrow 7$
- $7 \rightarrow 5 \rightarrow(b) 4 \rightarrow 7$
- $7 \rightarrow 5 \rightarrow 6 \rightarrow 7$
- $7 \rightarrow 5 \rightarrow 8 \rightarrow 7$
- $7 \rightarrow 6 \rightarrow 2 \rightarrow 7$
- $7 \rightarrow 6 \rightarrow 4 \rightarrow 7$
- $7 \rightarrow 6 \rightarrow 5 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 2 \rightarrow 7$
- $7 \rightarrow 8 \rightarrow 5 \rightarrow 7$

Vertex 8:

- $8 \rightarrow 2 \rightarrow 6 \rightarrow 8$
- $8 \rightarrow 2 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 5 \rightarrow 6 \rightarrow 8$
- $8 \rightarrow 5 \rightarrow 7 \rightarrow 8$
- $8 \rightarrow 6 \rightarrow 2 \rightarrow 8$
- $8 \rightarrow 6 \rightarrow 5 \rightarrow 8$
- $8 \rightarrow 7 \rightarrow 2 \rightarrow 8$
- $8 \rightarrow 7 \rightarrow 5 \rightarrow 8$

Vertex 9:

- $9 \rightarrow 1 \rightarrow 10 \rightarrow(a) 9$
- $9 \rightarrow 1 \rightarrow 10 \rightarrow(b) 9$
- $9 \rightarrow(a) 10 \rightarrow 1 \rightarrow 9$
- $9 \rightarrow(b) 10 \rightarrow 1 \rightarrow 9$

Vertex 10:

- $10 \rightarrow 1 \rightarrow 3 \rightarrow 10$
- $10 \rightarrow 3 \rightarrow 1 \rightarrow 10$
- $10 \rightarrow(a) 9 \rightarrow 1 \rightarrow 10$
- $10 \rightarrow(b) 9 \rightarrow 1 \rightarrow 10$

Vertex 11:

- $11 \rightarrow 1 \rightarrow 3 \rightarrow 11$
- $11 \rightarrow 1 \rightarrow 11 \rightarrow(c w) 11$
- $11 \rightarrow 1 \rightarrow 11 \rightarrow(c c w) 11$
- $11 \rightarrow 3 \rightarrow 1 \rightarrow 11$
- $11 \rightarrow 3 \rightarrow 11 \rightarrow(c w) 11$
- $11 \rightarrow 3 \rightarrow 11 \rightarrow(c c w) 11$
- $11 \rightarrow 4 \rightarrow 11 \rightarrow(c w) 11$
- $11 \rightarrow 4 \rightarrow 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow 1 \rightarrow 11$
- $11 \rightarrow(c w) 11 \rightarrow 3 \rightarrow 11$
- $11 \rightarrow(c w) 11 \rightarrow 4 \rightarrow 11$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow 1 \rightarrow 11$
- $11 \rightarrow(c c w) 11 \rightarrow 3 \rightarrow 11$
- $11 \rightarrow(c c w) 11 \rightarrow 4 \rightarrow 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c w) 11 \rightarrow(c c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c w) 11$
- $11 \rightarrow(c c w) 11 \rightarrow(c c w) 11 \rightarrow(c c w) 11$
$\mid$ Type III' $^{\prime} Z \mid=128$


## B Symmetric matrices have real eigenvalues

Our ultimate goal is to present the proof of the Fundamental Theorem of Real Symmetric Matrices. In order to do so, we must first present and provide the proofs of two other theorems that will be needed in this proof.

## B. 1 Schur's Lemma

We begin with the theorem known as Schur's Lemma. This will be used in the proof of the next preparatory theorem whose proof we will be working through.

Theorem B.1. Let $A$ be an $n \times n$ (complex) matrix. There is a unitary matrix $U$ such that $U^{-1} A U$ is upper triangular.

Proof. We will prove Schur's Lemma by induction.

If $n=1$, then Schur's Lemma is trivially true.

Let us assume this theorem holds for all $m \times m$ matrices such that $1 \leq m \leq$ ( $\mathrm{n}-1$ ).

We will now show that it holds for an $n \times n$ matrix $A$.

Let $\lambda_{1}$ be an eigenvalue of $A$, and let $\mathbf{v}_{1}$ be a corresponding unit eigenvector.

We know that $A$, and every complex matrix, will have at least 1 eigenvalue by the Fundamental Theorem of Algebra (Section 9.1 of [4]).

We now expand $\mathbf{v}_{1}$ so that it becomes a basis for $\mathbb{C}^{n}$ by choosing $\mathbf{v}_{2}, \ldots, \mathbf{v}_{n}$ so $\mathbf{v}_{1}, \ldots, \mathbf{v}_{n}$ is an orthonormal basis.

Using the Gram-Schmidt process we can then transform it into an orthonormal basis

$$
\mathbf{v}_{1}, \mathbf{v}_{2}, \ldots, \mathbf{v}_{n}
$$

Let $U_{1}$ be the unitary matrix with $j^{\text {th }}$ column vector $\mathbf{v}_{j}$. The first column vector of $A U_{1}$ will be $A \mathbf{v}_{1}=\lambda_{1} \mathbf{v}_{1}$.

We know the $i^{t h}$ row vector of $U_{1}^{*}$ is $\mathbf{v}_{i}^{*}$. Since the vectors $\mathbf{v}_{j}$ are orthogonal, $\mathbf{v}_{i}^{*} \mathbf{v}_{j}=0$ for $i \neq j$.

So the first column vector of $U_{1}^{*} A U_{1}$ will be

$$
U_{1}^{*}\left(\lambda_{1} \mathbf{v}_{1}\right)=\left(\begin{array}{c}
\lambda_{1} \\
0 \\
\vdots \\
\vdots \\
0
\end{array}\right)
$$

Using this, we can write

$$
U_{1}^{*} A U_{1}=\left(\begin{array}{cccccc}
\lambda_{1} & * & * & . . & . . & *  \tag{B.1}\\
0 & & & & & \\
0 & & & & & \\
\vdots & & & A_{1} & & \\
\vdots & & & & & \\
0 & & & & &
\end{array}\right)
$$

where $A_{1}$ is an $(n-1) \times(n-1)$ submatrix.

Our induction hypothesis indicates there is an $(n-1) \times(n-1)$ unitary matrix $C$ such that $C^{*} A_{1} C=B$ for an upper triangular matrix $B$.

Let

$$
U_{2}=\left(\begin{array}{cccccc}
1 & 0 & 0 & . . & . . & 0  \tag{B.2}\\
0 & & & & & \\
0 & & & & \\
\vdots & & & C & & \\
\vdots & & & & & \\
0 & & & & &
\end{array}\right)
$$

Since $C$ is unitary, we can show that $U_{2}$ is also a unitary matrix.

$$
\begin{aligned}
U_{2}^{*} U_{2}= & \left(\begin{array}{cccccc}
1 & 0 & 0 & . . & . . & 0 \\
0 & & & & & \\
0 & & & & & \\
\vdots & & & C^{*} & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)\left(\begin{array}{cccccc}
1 & 0 & 0 & . . & . . & 0 \\
0 & & & & & \\
0 & & & & & \\
\vdots & & & C & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right) \\
& =\left(\begin{array}{cccccc}
1 & 0 & 0 & . . & . . & 0 \\
0 & & & & & \\
0 & & & & \\
\vdots & & & C^{*} C & & \\
\vdots & & & & & \\
0 & &
\end{array}\right)
\end{aligned}
$$

$$
=\left(\begin{array}{cccccc}
1 & 0 & 0 & . . & . . & 0 \\
0 & & & & \\
0 & & & & & \\
\vdots & & & I & & \\
\vdots & & & & & \\
0 & & & & &
\end{array}\right)=I
$$

and thus $U_{2}$ is unitary.

We now consider $U=U_{1} U_{2}$ and calculate

$$
U^{*} U=U_{2}^{*}\left(U_{1}^{*} U_{1}\right) U_{2}=U_{2}^{*} I U_{2}=U_{2}^{*} U_{2}=I
$$

This indicates that $U$ is also unitary.

Using

$$
\begin{equation*}
U^{*} A U=U_{2}^{*} U_{1}^{*} A U_{1} U_{2} \tag{B.3}
\end{equation*}
$$

we can combine (2.3) with (2.1) and (2.2):

$$
\begin{aligned}
& U^{*} A U= \\
& \left(\begin{array}{ccccc}
1 & 0 & . . & . . & 0 \\
0 & & & & \\
\vdots & & C^{*} & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)\left(\begin{array}{ccccc}
\lambda_{1} & * & . . & . . & * \\
0 & & & & \\
\vdots & & A_{1} & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)\left(\begin{array}{ccccc}
1 & 0 & . . & . . & 0 \\
0 & & & & \\
\vdots & & C & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right) \\
& =\left(\begin{array}{ccccc}
\lambda_{1} & * & . . & . . & * \\
0 & & & & \\
\vdots & & C^{*} A_{1} & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)\left(\begin{array}{ccccc}
1 & 0 & . . & . . & 0 \\
0 & & & & \\
\vdots & & C & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)
\end{aligned}
$$

$$
=\left(\begin{array}{ccccc}
\lambda_{1} & * & . . & . . & * \\
0 & & & \\
\vdots & & C^{*} A_{1} C & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)
$$

We obtain

$$
U^{*} A U=\left(\begin{array}{ccccc}
\lambda_{1} & * & . . & . . & * \\
0 & & & & \\
\vdots & & B & & \\
\vdots & & & & \\
0 & & & &
\end{array}\right)
$$

Since $B$ is upper triangular, this tells us $U^{*} A U$ is upper triangular as well.

Now that we have completed this proof, we can use Schur's Lemma in the proof of the Spectral Theorem for Hermitian Matrices. This next theorem will then be used in the proof of the Fundamental Theorem of Real Symmetric Matrices.

## B. 2 Spectral Theorem for Hermitian Matrices

Theorem B.2. If $A$ is a Hermitian matrix, there exists a unitary matrix $U$ such that $U^{-1} A U$ is a diagonal matrix. Also, all eigenvalues of $A$ are real. Proof. We will begin by proving the first part of the theorem.

From Schur's Lemma, we have that there is a unitary matrix $U$ such that $U^{-1} A U$ is upper triangular.

Given that $U$ is unitary, we see that $U^{-1}=U^{*}$ and $U^{*} U=I$. Because $A$ is Hermitian, $A^{*}=A$.

So,

$$
\left(U^{-1} A U\right)^{*}=\left(U^{*} A U\right)^{*}=U^{*} A^{*}\left(U^{*}\right)^{*}=U^{*} A U=U^{-1} A U
$$

Therefore, $U^{-1} A U$ is Hermitian as well.

The conjugate transpose of an upper triangular matrix will be a lower triangular matrix. Knowing that $U^{-1} A U$ is Hermitian indicates it is both upper triangular and lower triangular, so it must be a diagonal matrix $D: U^{-1} A U=D$. Therefore, we now know that the matrix $A$ is unitarily diagonalizable, $U^{-1} A U=$ D.

We can now show that the eigenvalues of $A$ are real. Since $D$ is a diagonal matrix, we know that the entries along it's diagonal will be the eigenvalues of A.

We also know that $D$ is Hermitian, so $D=D^{*}$

$$
D=\left(\begin{array}{cccccc}
\lambda_{1} & 0 & 0 & . & . & 0 \\
& \lambda_{2} & & & \cdot & \cdot \\
\cdot & & \cdot & & & \cdot \\
\cdot & & & \cdot & & . \\
. & & & . & 0 \\
0 & \cdot & . & . & 0 & \lambda_{n}
\end{array}\right)
$$

$$
D^{*}=\left(\begin{array}{cccccc}
\lambda_{1}^{*} & 0 & 0 & \cdot & \cdot & 0 \\
& \lambda_{2}^{*} & & & \cdot & \cdot \\
\cdot & & \cdot & & & \cdot \\
\cdot & & & \cdot & & \cdot \\
\cdot & & & & \cdot & 0 \\
0 & \cdot & \cdot & \cdot & 0 & \lambda_{n}^{*}
\end{array}\right)
$$

Since $D=D^{*}, \lambda_{j}=\lambda_{j}^{*}$ for $j=1, \ldots, n$.

Therefore, the eigenvalues $\lambda_{1}, \ldots, \lambda_{n}$ must be real.

We are now able to use this important conclusion in the proof of the Fundamental Theorem of Real Symmetric Matrices.

## B. 3 Fundamental Theorem of Real Symmetric Matrices

Theorem B.3. Every $n \times n$ real symmetric matrix has $n$ real eigenvalues (counted with algebraic multiplicity) and is diagonalizable by a real orthogonal matrix.

Proof. We know every real $n \times n$ symmetric matrix $A$ is also Hermitian.

By the Spectral Theorem for Hermitian Matrices, $A$ is diagonalizable with real eigenvalues $\lambda_{1}, \ldots, \lambda_{n}$.

Therefore, $A$ has $n$ real eigenvalues counted with algebraic multiplicity.

We must count the eigenvalues with multiplicity as a result of the following theorem found on p. 313 of [4].

Theorem B.4. A Criterion for Diagonalization: An $n \times n$ matrix $A$ is diagonalizable if and only if the algebraic multiplicity of each (possibly complex) eigenvalue is equal to its geometric multiplicity.

From the Spectral Theorem for Hermitian Matrices we also know that $A$ is unitarily diagonalizable. We will let it be diagonalized by the unitary matrix $U$.

By Theorem 5.2 of [4], Matrix Summary of Eigenvalues of A, and its proof (p.306), the column vectors of $U$ will be eigenvectors of $A$. We can determine these eigenvectors by row-reducing $A-\lambda_{i} I$ for $i=1, \ldots, n$.

We have already proved the $\lambda_{i}$ are real. We will now row-reduce over the real numbers.

This tells us the row-reduced echelon form of $A-\lambda_{i} I$ will have only real elements.

This will be best illustrated through an example.

Example: Let

$$
A=\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 2 & 0 \\
1 & 0 & 1
\end{array}\right)
$$

We will first determine the eigenvalues of $A$ and their corresponding row-
reduced echelon forms of $A-\lambda_{i} I$.

The characteristic polynomial of $A$ is:

$$
\begin{aligned}
\operatorname{det}(A-\lambda I) & =\operatorname{det}\left(\begin{array}{ccc}
1-\lambda & 0 & 1 \\
0 & 2-\lambda & 0 \\
1 & 0 & 1-\lambda
\end{array}\right) \\
& =(2-\lambda)\left[(1-\lambda)^{2}-1\right]
\end{aligned}
$$

$$
=-\lambda(\lambda-2)^{2}
$$

$$
\lambda_{1}=0, \lambda_{2}=\lambda_{3}=2
$$

Now that we have found the eigenvalues of $A$, we can determine the rowreduced echelon forms of the $A-\lambda_{i} I$ and show all their entries are real numbers.

$$
\begin{gathered}
\lambda_{1}=0 \\
A-\lambda_{1} I=\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 2 & 0 \\
1 & 0 & 1
\end{array}\right) \sim\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 1 & 0 \\
0 & 0 & 0
\end{array}\right) \\
\lambda_{2}=\lambda_{3}=2 \\
A-2=\left(\begin{array}{ccc}
-1 & 0 & 1 \\
0 & 0 & 0 \\
1 & 0 & -1
\end{array}\right) \sim\left(\begin{array}{ccc}
1 & 0 & -1 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{array}\right)
\end{gathered}
$$

Thus showing the row-reduced echelon forms of $A-\lambda_{i} I$ contain only real entries.

Since $A$ is diagonalizable, $A-\lambda_{i} I$ in row-reduced echelon form will have

$$
\operatorname{dim}(\text { nullspace })=\text { geometric multiplicity of } \lambda_{i}
$$

geometric multiplicity of $\lambda_{i}=$ algebraic multiplicity of $\lambda_{i}$. If, for $M=A-\lambda_{i} I, M$ is an $n \times n$ real matrix with $\operatorname{rank} M=k \leq n$, then the nullspace of $M$ is a subspace of $\mathbb{R}^{n}$ of dimension $n-k$. Therefore the nullspace of $M$ has a basis consisting of vectors in $\mathbb{R}^{n}$.

The Gram-Schmidt process lets us assume the basis of each eigenspace is orthonormal.

If we let vectors of these orthonormal bases of the eigenspaces form the columns of the matrices, $C_{1}, C_{2}, \ldots, C_{r}$, we obtain a real orthogonal matrix $C$ that diagonalizes $A$.

$$
C=\left(\begin{array}{ccccc}
C_{1} & & & & \\
& C_{2} & & & \\
& & \cdot & & \\
& & & & \\
& & & \cdot & \\
& & & & C_{r}
\end{array}\right)
$$

## References

[1] Allan Clark. Elements of Abstract Algebra. Dover Publications, Mineola, NY, 1984.
[2] Debra Czarneski. Zeta Functions of Finite Graphs. PhD Dissertation, Louisiana State University. August 2005.
[3] Susanna S. Epp. Discrete Mathematics with Applications. PWS Publishing Company, Boston, second edition, 1995.
[4] John B. Fraleigh and Raymond A. Bauregard Linear Algebra 3rd Edition. 1995: Addison-Wesley Publsihing Company, Reading, MA.
[5] C.D. Godsill and B.D. McKay. Constructing Cospectral Graphs. Aequationes Mathematicae, 25:257-268, 1982.
[6] Robert Perlis. Finite Graphs and their Zeta Functions. Lecture at Louisiana State University, transcribed by Christopher Belford. Baton Rouge, 12 June 2003.
[7] Gregory Quenell. The Combinatorics of Seidel Switching. Preprint, December 16, 1997.
[8] Audrey Terras. Fourier Analysis on Finite Groups and Applications. London Mathematical Society Student Texts 43. Cambridge University Press, New York, NY, 1999.
[9] J.H. van Lint and J.J. Seidel. Equilateral point sets in elliptic geometry. Proceedings. Koninklijke Nederlanse Academie van Wetenschppen, Series A, 69:335-348, 1966.
[10] Eric W. Weisstein. "Isospectral Graphs." From MathWorld-A Wolfram Web Resource. http://mathworld.wolfram.com/IsospectralGraphs.html
[11] Douglas B. West. Introduction to Graph Theory. Prentice Hall, Upper Saddle River, NJ, second edition, 2001.


[^0]:    ${ }^{1}$ In $[7]$ the term isospectral is used, while other sources use cospectral. Since we will be referring to pairs of graphs, the term cospectral will be used for consistency.

[^1]:    ${ }^{2}$ We use $Q=q I$ because $\Gamma$ is regular. For a non-regular graph, $Q$ is the diagonal matrix such that each $a_{i i}$ along the diagonal is equal to the degree $q+1_{i}$ minus 1 at each vertex $v_{i}$ of $\Gamma$.

